

IMPULSES AND PHYSIOLOGICAL STATES IN THEORETICAL MODELS OF NERVE MEMBRANE

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The following linear differential equation describes an oscillating quantity x with damping constant k (the dots represent differentiation with respect to time t):

$$\ddot{x} + k\dot{x} + x = 0$$

Van der Pol (1926) replaced the damping constant by a damping coefficient which depends quadratically on x :

$$\ddot{x} + c(x^2 - 1)\dot{x} + x = 0$$

where c is a positive constant. It is convenient to use Liénard's transformation (Liénard, 1928; Minorsky, 1947):

$$y = \dot{x}/c + x^3/3 - x$$

and obtain the following pair of differential equations:

$$\dot{x} = c(y + x - x^3/3)$$

$$\dot{y} = -x/c$$

The BVP model is obtained by adding terms to these equations as follows:—

$$\dot{x} = c(y + x - x^3/3 + z) \quad (1)$$

$$\dot{y} = -(x - a + by)/c \quad (2)$$

1962

PROCEEDINGS OF THE IRE

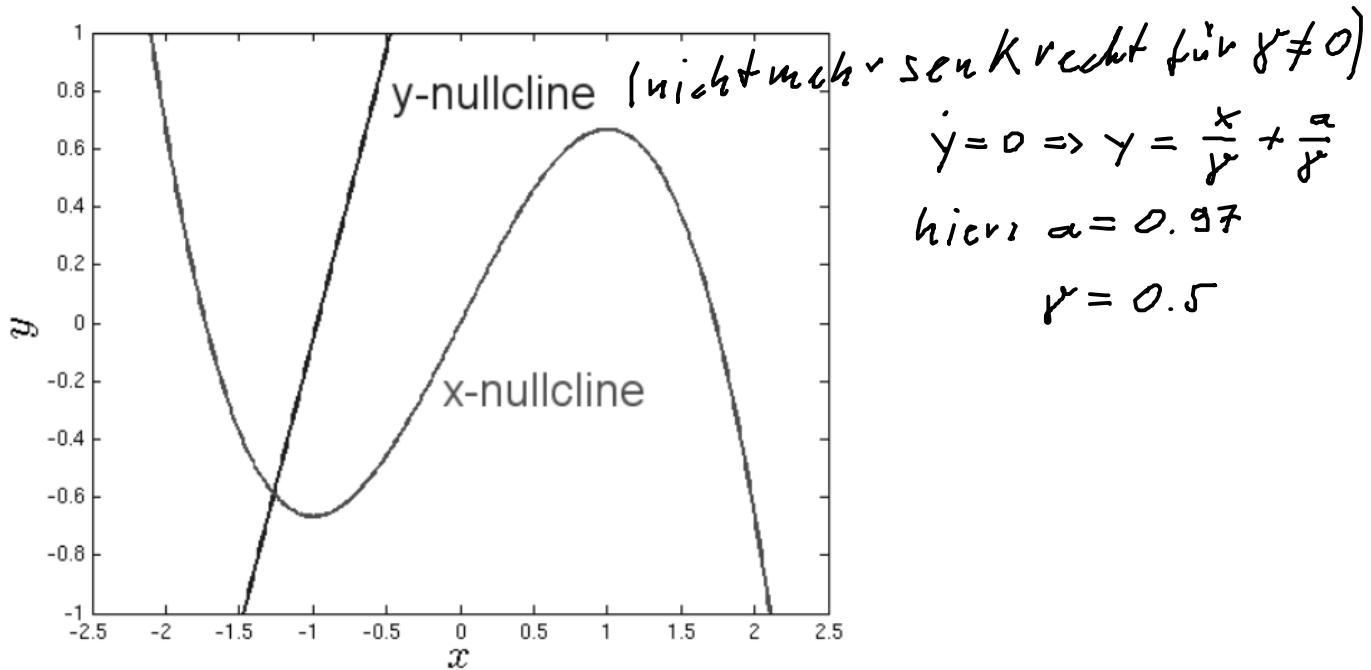
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An Active Pulse Transmission Line Simulating Nerve Axon*

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Recently, FitzHugh ingeniously simplified the H-H equations in case of a “space clamp,” making use of an analog computer, and proposed the following BVP model (Bonhoeffer-van der Pol model).⁹

$$\begin{cases} J = \frac{1}{c} \frac{du}{dt} - w - \left(u - \frac{u^3}{3} \right), \\ c \frac{dw}{dt} + bw = a - u, \end{cases} \quad (2)$$

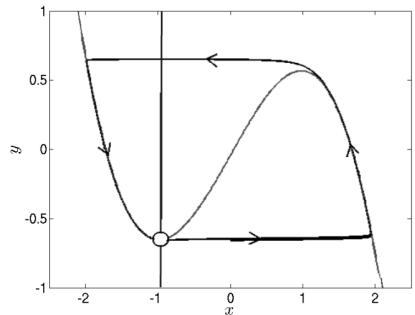
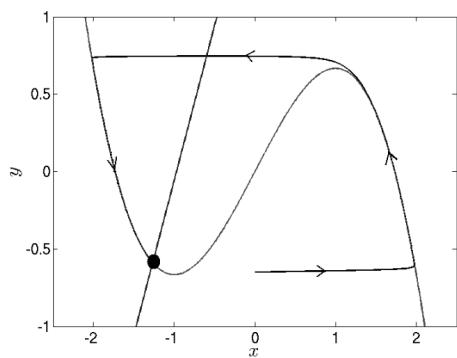
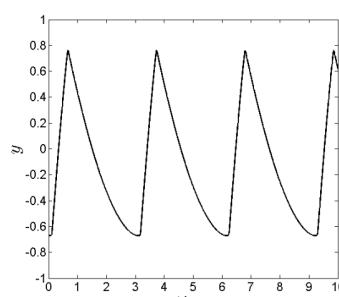
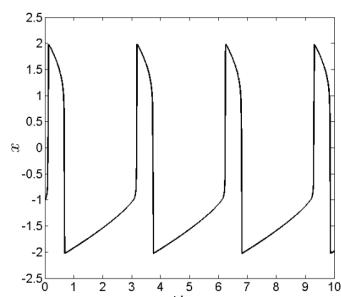
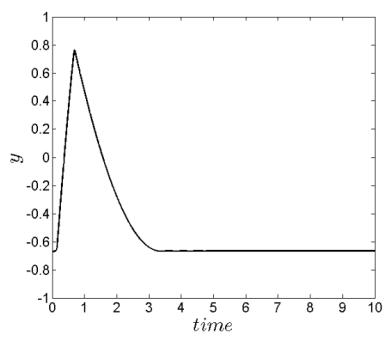
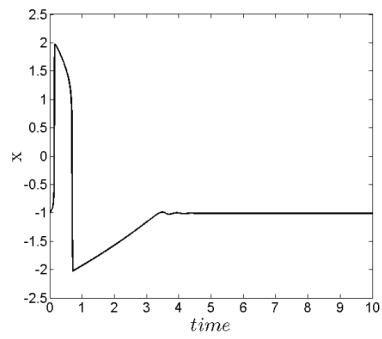


Bestimmung von (x^*, y^*) : $0 = -\frac{\alpha}{\gamma} + \left(1 - \frac{1}{\gamma}\right)x^* - \frac{(x^*)^3}{3}$

Nullstellen einer kubischen Gleichung

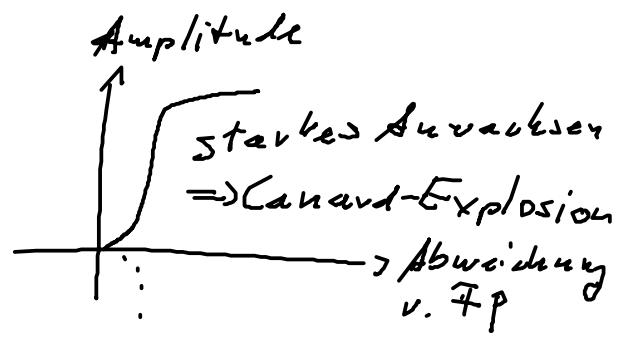
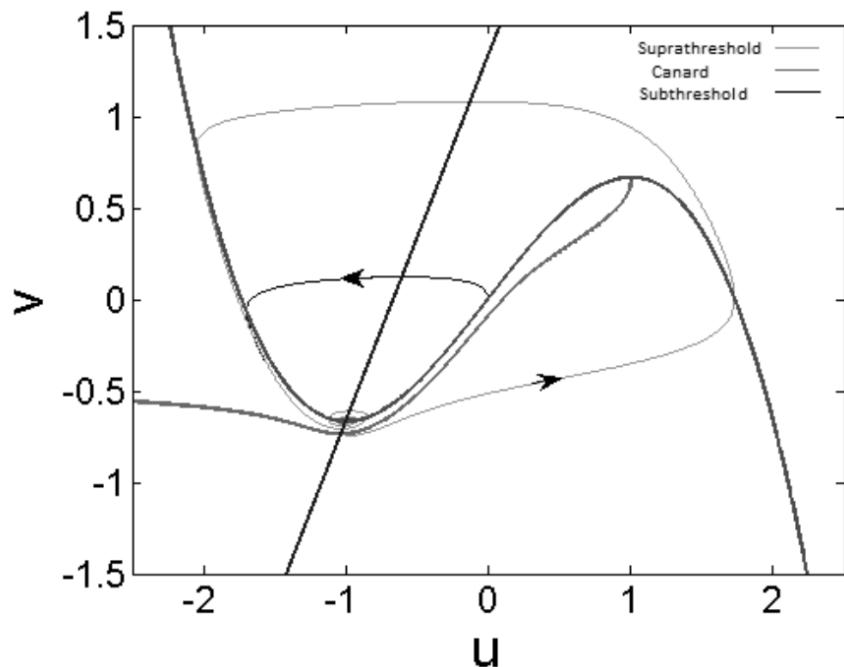
$$\begin{pmatrix} \delta x \\ \delta y \end{pmatrix} = \begin{pmatrix} \frac{1-x^*}{\epsilon}^2 & -\frac{1}{\epsilon} \\ 1 & -\gamma \end{pmatrix} \begin{pmatrix} \delta x \\ \delta y \end{pmatrix} \Rightarrow \lambda_{1,2} = \frac{t_{1,2} \pm \sqrt{(t_{1,2})^2 - 4 \det J}}{2}$$

Rolle von Parameter γ :



oszillierend: $\epsilon = 0.005$, $\alpha = 0.97$
 $r = 0.005$

unregbar: $\epsilon = 0.005$, $\alpha = 0.97$, $r = 0.5$



$$\alpha = 0.67 \\ r = 0.5$$