

## 4. Vector calculus / analysis

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### 4.1 (Conservative) vector fields

- Vectorfield:  $V: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $x \mapsto \underline{v}(x) = \begin{pmatrix} v_1(x) \\ \vdots \\ v_n(x) \end{pmatrix}$
- $C^1$ -vectorfield:  $v_1, \dots, v_n$   $\overset{\text{potentially chosen } \Omega \subset \mathbb{R}^n}{\text{S-func}}$  continuously differentiable.
- Conservative vectorfield:  $\underline{v}$  is gradient of scalar potential  $\phi$

$$\underline{v}(x) = \underline{\nabla} \phi(x)$$

### 4.2 Derivatives of vectorfields

- (Rotation) curl of  $\underline{v}(x) = \begin{pmatrix} v_1(x) \\ v_2(x) \\ v_3(x) \end{pmatrix}$ :

$$\text{rot } \underline{v} \equiv \underline{\nabla} \times \underline{v} := \begin{pmatrix} \partial_1 \\ \partial_2 \\ \partial_3 \end{pmatrix} \times \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} \partial_2 v_3 - \partial_3 v_2 \\ \partial_3 v_1 - \partial_1 v_3 \\ \partial_1 v_2 - \partial_2 v_1 \end{pmatrix}$$

$$(\text{rot } \underline{v})_i = \sum_{j,k=1}^3 \epsilon_{ijk} \partial_j v_k$$

- Divergence of  $\underline{v}(x)$ :  $\text{div } \underline{v}(x) = \underline{\nabla} \cdot \underline{v} := \frac{\partial}{\partial x_1} v_1 + \frac{\partial}{\partial x_2} v_2 + \frac{\partial}{\partial x_3} v_3$

(iii) Def: Der Laplace-Operator ist definiert als:  $\Delta := \text{div grad}$

$$\text{Also: } \Delta \phi(x_1, x_2, x_3) = \nabla \cdot (\nabla \phi) = (\partial_{x_1}, \partial_{x_2}, \partial_{x_3}) \cdot \begin{pmatrix} \partial_{x_1} \phi \\ \partial_{x_2} \phi \\ \partial_{x_3} \phi \end{pmatrix}$$

$$= \frac{\partial^2}{\partial x_1^2} \phi + \frac{\partial^2}{\partial x_2^2} \phi + \frac{\partial^2}{\partial x_3^2} \phi$$

↳ Laplace-Gleichung:  $\Delta \phi = 0$  (wichtig bei Transportprozesse, Potentialtheorie...)

Ableitung:  $\Delta \underline{A} = \frac{\partial^2 \underline{A}}{\partial x_1^2} + \frac{\partial^2 \underline{A}}{\partial x_2^2} + \frac{\partial^2 \underline{A}}{\partial x_3^2} = \text{grad div } \underline{A} - \text{rot rot } \underline{A} = \nabla (\nabla \cdot \underline{A}) - \nabla \times (\nabla \times \underline{A})$

Bem: •  $\text{div}, \text{rot}, \text{grad}$  sind linear:  $\text{rot}(\underline{u} + \underline{v}) = \text{rot } \underline{u} + \text{rot } \underline{v}$   
 $\text{div}(\underline{u} + \underline{v}) = \text{div } \underline{u} + \text{div } \underline{v}$   
 $\text{grad}(\phi + \psi) = \text{grad } \phi + \text{grad } \psi$

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• Produktregel:  $\text{div}(\phi \underline{v}) = \phi \text{div } \underline{v} + (\text{grad } \phi) \cdot \underline{v}$   
 $\text{rot}(\phi \underline{A}) = \nabla \phi \times \underline{A} + \phi (\nabla \times \underline{A}) = \text{grad } \phi \times \underline{A} + \phi \text{rot } \underline{A}$

4.3 Gradienten- & Wirbelfelder

Satz: Gradientenfelder  $\underline{v} = \nabla \phi$  sind wirbelfrei.

Beweis:  $\text{rot } \underline{v} = \nabla \times \underline{v} = \nabla \times (\nabla \phi)$

i-te Komponente:  $[\nabla \times \nabla \phi]_i = \epsilon_{ijk} \partial_j (\nabla \phi)_k$

$$= \underbrace{\epsilon_{ijk}}_{\text{antisym.}} \underbrace{\partial_j \partial_k \phi}_{\text{symmetrisch}} = 0$$

Also: (i)  $\text{rot grad} = \nabla \times \nabla = 0$

(ii) Umkehrung gilt auch: Jedes wirbelfreie Feld  $\underline{v}$  hat ein Potential  $\phi$  ( $\text{rot } \underline{v} = 0$ ) ( $\underline{v} = \nabla \phi$ )

$\Rightarrow \underline{v}$  ist konservativ  $(\Leftrightarrow \text{rot } \underline{v} = 0)$

Bsp:  $\underline{A}(x) = \begin{pmatrix} -y^3 z^2 \\ x e^{2z} \\ e^{2y} \end{pmatrix} \Rightarrow$  Berechne  $\Delta \underline{A}$  (Laplace-Operator)

$$\Rightarrow \Delta \underline{A} = \frac{\partial}{\partial x} \begin{pmatrix} 0 \\ e^{2z} \\ 0 \end{pmatrix} + \frac{\partial}{\partial y} \begin{pmatrix} -3y^2 z \\ 0 \\ 2e^{2y} \end{pmatrix} + \frac{\partial}{\partial z} \begin{pmatrix} -y^3 \\ x e^{2z} \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -6yz \\ 0 \\ 4e^{2y} \end{pmatrix} + \begin{pmatrix} 0 \\ x e^{2z} \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} -6yz \\ x e^{2z} \\ 4e^{2y} \end{pmatrix}$$

$$\underline{\nabla}(\underline{\nabla} \cdot \underline{A}) = \underline{\nabla} \left( \frac{\partial}{\partial x} A_1 + \frac{\partial}{\partial y} A_2 + \frac{\partial}{\partial z} A_3 \right) =$$

$$= \underline{\nabla} \left( \frac{\partial}{\partial x} (-y^3 z^2) + \frac{\partial}{\partial y} (x e^{2z}) + \frac{\partial}{\partial z} (e^{2y}) \right)$$

$$= \underline{\nabla} (0) = \underline{0}$$

$$- \underline{\nabla} \times (\underline{\nabla} \times \underline{A}) = \underline{\nabla} \times \begin{pmatrix} 2e^{2y} & -x e^{2z} \\ -y^3 & 0 \\ e^{2z} & +3y^2 z \end{pmatrix} = \underline{\nabla} \times \begin{pmatrix} 2e^{2y} - x e^{2z} \\ -y^3 \\ e^{2z} + 3y^2 z \end{pmatrix}$$

$$= - \begin{pmatrix} 6yz & 0 \\ x e^{2z} & 0 \\ 0 & -4e^{2y} \end{pmatrix} = \begin{pmatrix} -6yz \\ x e^{2z} \\ 4e^{2y} \end{pmatrix}$$

$\Rightarrow \Delta \underline{A} = \text{grad div } \underline{A} - \text{rot rot } \underline{A}$

Satz: Wirbelfelder  $\underline{v} = \text{rot } \underline{A}$  sind quellfrei.

Beweis:  $\text{div } \underline{v} = \text{div}(\text{rot } \underline{A}) = \underline{\nabla} \cdot \underline{\nabla} \underline{A} = \sum_i \partial_i (\underline{\nabla} \times \underline{A})_i$

$$= \sum_{ijk} \partial_i \epsilon_{ijk} \partial_j A_k$$

$$= 0$$

Also: (i)  $\text{div rot} = 0$

(ii) Umkehrung gilt auch: Jede quellfreie Feld hat ein Vektorpotential.

Bz.B:  $\underline{B} = \underline{\nabla} \times \underline{A}$

Anwendung: Maxwell-Gleichungen (homogen)

(a)  $\underline{\nabla} \cdot \underline{B} = 0$       (b)  $\underline{\nabla} \times \underline{E} + \frac{\partial \underline{B}}{\partial t} = 0$

mit  $\underline{B} = \underline{\nabla} \times \underline{A}$ :  $\underline{\nabla} \times \underline{E} + \frac{\partial}{\partial t} \underline{\nabla} \times \underline{A} = 0$

Setzen  
Schwarz  $\left. \vphantom{\begin{matrix} \text{Setzen} \\ \text{Schwarz} \end{matrix}} \right\} \underline{\nabla} \times \left( \underline{E} + \frac{\partial \underline{A}}{\partial t} \right) = 0$

Wirbelfrei  $\left. \vphantom{\begin{matrix} \text{Wirbelfrei} \end{matrix}} \right\} \underline{E} + \frac{\partial \underline{A}}{\partial t} = -\underline{\nabla} \phi$  ↙ potentiell

$\Rightarrow \underline{B} = \underline{\nabla} \times \underline{A}$

$\underline{E} = -\underline{\nabla} \phi - \frac{\partial \underline{A}}{\partial t}$  ( $\phi, \underline{A}$  nicht eindeutig  
↳ Eichtransformationen)