

5.3 Symplectic structure of the phase space

Sta

idea! find ^{canonical} transformations that leave the Hamiltonian equations $\dot{q}_j = \frac{\partial H(q_1, \dots, q_n, p_1, \dots, p_n, t)}{\partial p_j}$, $\dot{p}_j = -\frac{\partial H}{\partial q_j}$

form in variant: $(q, p) \rightarrow (P, Q)$

• core Hamilton principle: $\int_{t_1}^{t_2} d\tau L = \int_{t_1}^{t_2} d\tau \left\{ \sum_{j=1}^n p_j \dot{q}_j - H(q, p, t) \right\} = 0$
 4 equivalent forms of generating functions of canonical transformations:

(i) $M_1(q, Q, t) : p_j = \frac{\partial M_1}{\partial q_j}, \quad P_j = -\frac{\partial M_1}{\partial Q_j}$

$\bar{H} = H + \frac{\partial M_1}{\partial t}$

$\Rightarrow \frac{\partial P_j}{\partial Q_k} = \frac{\partial^2 M_1}{\partial Q_k \partial q_j} = -\frac{\partial P_k}{\partial q_j}$

(ii) $M_2(q, P, t) : p_j = \frac{\partial M_2}{\partial q_j}, \quad Q_j = \frac{\partial M_2}{\partial P_j}$

$= M_1(q, Q, t) - \sum_{j=1}^n \frac{\partial M_1}{\partial Q_j} Q_j$
 Legendre
 bz bz bz

$\Rightarrow \frac{\partial P_j}{\partial P_k} = \frac{\partial^2 M_2}{\partial P_k \partial q_j} = \frac{\partial Q_k}{\partial q_j}$

(iii) $M_3(P, Q, t) : q_j = -\frac{\partial M_3}{\partial P_j}, \quad P_j = -\frac{\partial M_3}{\partial Q_j}$

$= M_1 - \sum_{j=1}^n \frac{\partial M_1}{\partial q_j} q_j$
 Legendre
 bz bz bz

$\Rightarrow \frac{\partial q_j}{\partial Q_k} = -\frac{\partial^2 M_3}{\partial Q_k \partial P_j} = \frac{\partial P_k}{\partial P_j}$

(iv) $M_4(P, P, t) : q_j = -\frac{\partial M_4}{\partial P_j}, \quad Q_j = \frac{\partial M_4}{\partial P_j}$

Legendre bz bz
 Q_j and q_j

$\Rightarrow \frac{\partial q_j}{\partial P_k} = -\frac{\partial^2 M_4}{\partial P_k \partial P_j} = -\frac{\partial Q_k}{\partial P_j}$

$$\underline{x} = \begin{pmatrix} q \\ p \end{pmatrix}, \quad \underline{H}_x = \begin{pmatrix} \frac{\partial H}{\partial q} \\ \frac{\partial H}{\partial p} \end{pmatrix}, \quad \underline{J} = \begin{pmatrix} 0 & \underline{1} \\ -\underline{1} & 0 \end{pmatrix}$$

$$\Rightarrow \dot{\underline{x}} = \underline{J} \underline{H}_x \Leftrightarrow \dot{q}_j = \frac{\partial H}{\partial p_j}, \quad \dot{p}_j = -\frac{\partial H}{\partial q_j}$$

$$\underline{J}^2 = -\underline{1}, \quad \underline{J}^{-1} = \underline{J}^T = -\underline{J}$$

$$\Rightarrow \underline{J} \dot{\underline{x}} = \underline{H}_x$$

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 mit $\underline{x} = \begin{pmatrix} q_1 \\ \vdots \\ q_k \\ p_1 \\ \vdots \\ p_l \end{pmatrix}$, $\underline{y} = \begin{pmatrix} Q_1 \\ \vdots \\ Q_k \\ P_1 \\ \vdots \\ P_l \end{pmatrix}$ und $M_{\alpha\beta} = \frac{\partial x_\alpha}{\partial y_\beta}$, $(M^{-1})_{\alpha\beta} = \frac{\partial y_\alpha}{\partial x_\beta}$ folgt:
 $\alpha, \beta = 1, \dots, 2l$

$$M_{\alpha\beta} = \sum_{\mu, \nu=1}^{2l} \Gamma_{\alpha\mu} \Gamma_{\beta\nu} (M^{-1})_{\nu\mu}$$

$$\Leftrightarrow \underline{M} = \underline{\Gamma} (\underline{\Gamma} \underline{M}^{-1})^T \Leftrightarrow \underline{M}^T \underline{\Gamma} \underline{M} = \underline{\Gamma} \quad \text{metrischer Tensor}$$

$\underline{\Gamma}$ „symplekt. Metrik“ über das verallgemeinerte schiefssymmetrische Skalarprodukt
 $(\underline{x}, \underline{y}) = \underline{x}^T \underline{\Gamma} \underline{y} = \sum_{i,k=1}^{2l} x_i \Gamma_{ik} y_k$
 (i) schiefssymmetrisch: $(\underline{y}, \underline{x}) = -(\underline{x}, \underline{y})$
 (ii) bilinear: $(\underline{x}, \lambda_1 \underline{y}_1 + \lambda_2 \underline{y}_2) = \lambda_1 (\underline{x}, \underline{y}_1) + \lambda_2 (\underline{x}, \underline{y}_2)$
 (iii) nicht entartet: $(\underline{x}, \underline{y}) = 0 \ \forall \underline{y} \Rightarrow \underline{x} = 0$
 (iv) $(\underline{x}, \underline{x}) = 0$ Selbstorthogonal

Fazit: Die (Form-)Invarianz der kanonischen Gleichungen

$\underline{\dot{x}} = \underline{\Gamma} \underline{H}_x$ unter kanonischen Transformations kann durch die symplektische Struktur o. Poisson-Klammer beschrieben werden.

$$\begin{aligned} \dot{y}_j &= \sum_k \frac{\partial y_j}{\partial x_k} \dot{x}_k & \Rightarrow \underline{\dot{y}} &= \underline{M}^{-1} \underline{\dot{x}} = \underline{M}^{-1} \underline{\Gamma} \underline{H}_x \\ \frac{\partial y_j}{\partial x_i} &= \sum_k \frac{\partial y_j}{\partial x_k} \frac{\partial x_k}{\partial y_i} & \Rightarrow \underline{H}_y &= \underline{M}^T \underline{H}_x \\ & & \underline{H}_x &= (\underline{M}^T)^{-1} \underline{H}_y \end{aligned}$$

$$\underline{M}^{-1} \underline{M} = (\underline{\Gamma}^{-1} \underline{M}^T \underline{\Gamma}) \underline{M} = \underline{\Gamma}^{-1} (\underline{M}^T \underline{\Gamma} \underline{M}) \stackrel{\underline{\Gamma}^T = -\underline{\Gamma}}{=} \underline{\Gamma}^{-1} \underline{\Gamma} = \underline{1}$$

$$\underline{M} = \underline{J} (\underline{J} \underline{M}^{-1})^T$$

$$\underline{M} = \begin{pmatrix} \frac{\partial q_1}{\partial q_1} & \frac{\partial q_1}{\partial q_2} & \dots & \frac{\partial q_1}{\partial q_f} & \frac{\partial q_1}{\partial P_1} & \dots & \frac{\partial q_1}{\partial P_f} \\ \frac{\partial q_2}{\partial q_1} & \frac{\partial q_2}{\partial q_2} & \dots & \frac{\partial q_2}{\partial q_f} & \frac{\partial q_2}{\partial P_1} & \dots & \frac{\partial q_2}{\partial P_f} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial q_f}{\partial q_1} & \frac{\partial q_f}{\partial q_2} & \dots & \frac{\partial q_f}{\partial q_f} & \frac{\partial q_f}{\partial P_1} & \dots & \frac{\partial q_f}{\partial P_f} \\ \hline \frac{\partial P_1}{\partial q_1} & \frac{\partial P_1}{\partial q_2} & \dots & \frac{\partial P_1}{\partial q_f} & \frac{\partial P_1}{\partial P_1} & \dots & \frac{\partial P_1}{\partial P_f} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial P_f}{\partial q_1} & \frac{\partial P_f}{\partial q_2} & \dots & \frac{\partial P_f}{\partial q_f} & \frac{\partial P_f}{\partial P_1} & \dots & \frac{\partial P_f}{\partial P_f} \end{pmatrix}$$

$$= \left(\begin{array}{c|c} \frac{\partial q}{\partial q} & \frac{\partial q}{\partial P} \\ \hline \frac{\partial P}{\partial q} & \frac{\partial P}{\partial P} \end{array} \right)$$

$$\underline{A} = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & & \vdots \\ \vdots & & \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$$

$$\underline{J} (\underline{J} \underline{M}^{-1})^T = \begin{pmatrix} \underline{0} & \underline{1} \\ -\underline{1} & \underline{0} \end{pmatrix} \left[\begin{pmatrix} \underline{0} & \underline{1} \\ -\underline{1} & \underline{0} \end{pmatrix} \begin{pmatrix} \frac{\partial q}{\partial q} & \frac{\partial q}{\partial P} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial P} \end{pmatrix} \right]^T$$

$$= \begin{pmatrix} \underline{0} & \underline{1} \\ -\underline{1} & \underline{0} \end{pmatrix} \left[\begin{pmatrix} \underline{0} & \underline{1} \\ \underline{1} & \underline{0} \end{pmatrix} \begin{pmatrix} \frac{\partial q}{\partial q} & \frac{\partial q}{\partial P} \\ \frac{\partial P}{\partial q} & \frac{\partial P}{\partial P} \end{pmatrix} \right]^T$$

$$= \begin{pmatrix} \underline{0} & \underline{1} \\ -\underline{1} & \underline{0} \end{pmatrix} \begin{pmatrix} \frac{\partial P}{\partial q} & \frac{\partial P}{\partial P} \\ -\frac{\partial q}{\partial q} & -\frac{\partial q}{\partial P} \end{pmatrix}^T$$

$$= \begin{pmatrix} \underline{0} & \underline{1} \\ -\underline{1} & \underline{0} \end{pmatrix} \begin{pmatrix} \left(\frac{\partial P}{\partial q}\right)^T & \left(\frac{\partial q}{\partial q}\right)^T \\ \left(\frac{\partial P}{\partial P}\right)^T & \left(\frac{\partial q}{\partial P}\right)^T \end{pmatrix} = \begin{pmatrix} \left(\frac{\partial P}{\partial P}\right)^T & -\left(\frac{\partial q}{\partial P}\right)^T \\ -\left(\frac{\partial P}{\partial q}\right)^T & \left(\frac{\partial q}{\partial q}\right)^T \end{pmatrix}$$

Test: Oben links Quadrant

$$\frac{\partial q_i}{\partial p_k} = - \left(\frac{\partial p_j}{\partial p_k} \right)^T = \frac{\partial p_k}{\partial p_j} \quad (M_3)$$

oben rechts:

$$\frac{\partial q_i}{\partial p_k} = - \left(\frac{\partial q_j}{\partial p_k} \right)^T = - \frac{\partial q_k}{\partial p_j} \quad (M_4)$$

unten links:

$$\frac{\partial p_j}{\partial q_k} = \left(\frac{\partial p_j}{\partial q_k} \right)^T = - \frac{\partial p_k}{\partial q_j} \quad (M_1)$$

unten rechts:

$$\frac{\partial p_j}{\partial p_k} = \left(\frac{\partial q_j}{\partial q_k} \right)^T = \frac{\partial q_k}{\partial q_j} \quad (M_2)$$

$$\underline{M} = \underline{J} (\underline{J} \underline{M}')^T \quad | \cdot \underline{J} \quad (\underline{J}^2 = \underline{1})$$

$$\underline{J} \underline{M} = -\underline{1} (\underline{J} \underline{M}')^T$$

$$= - (\underline{M}')^T \underline{J}^T \quad | \cdot \underline{M}^T$$

$$\underline{M}^T \underline{J} \underline{M} = - \underbrace{\underline{M}^T (\underline{M}')^T}_{(\underline{M}^{-1} \underline{M})^T = \underline{1}} \underline{J}^T = -\underline{J}^T = \underline{J}$$

$$\Rightarrow \underline{M}^T \underline{J} \underline{M} = \underline{J}$$

Def: Die Menge der Matrizen $\underline{M}$ (kann auch $\mathbb{J}$ sein)
mit $\underline{M}^T \underline{J} \underline{M} = \underline{J}$ bildet die reelle **symplektische**
Gruppe $\mathbb{J}$ über $\mathbb{R}^{2k}$ (Symplektische Gruppe der symplektischen
Struktur)