phase_space_pendulum_students

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```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        from scipy.integrate import solve_ivp
        from scipy.special import ellipk
In [ ]: def eq_of_motion(t, y, omega):
            # remove the pass keyword before you implement your solution
            pass
In [ ]: def phase_space_trajectory(y_init, omega = 1.0, has_initial_momentum: bool
            T = 4.0 / \text{omega} * \text{ellipk}(np.sin(0.5 * y_init[0]))
            if has_initial_momentum:
                T = 0.25 * T
            t_{span} = [0.0, T]
            t_eval = np.linspace(t_span[0], t_span[1], 5000)
            sol = solve_ivp(eq_of_motion, t_span, y_init, t_eval=t_eval, dense_outp
            t, p = sol.y
            return t, p
```

Explanation of meshgrid: To evaluate a multi-argument function f(x, y), we need a grid of points with repeating x and y values:

```
\begin{pmatrix} (x_1, y_1) & \dots & (x_N, y_1) \\ (x_1, y_2) & \dots & (x_N, y_2) \\ \vdots & \vdots & \vdots \\ (x_1, y_M) & \dots & (x_N, y_M) \end{pmatrix}.
```

numpy helps us generating such a grid from 1D-arrays $v_x = [x_1, \ldots, x_N]$ and $v_y = [y_1, \ldots, y_M]$ via meshgrid. The function repeats v_x as a row M times and v_y as a column N times, resulting in two $M \times N$ arrays. When passing these 2D-arrays (T and P in the cell below) to a function, it iterates over the entries one by one resulting in the desired point grid described at the start.

```
In [ ]: # set a default value for the pendulum frequnecy
   omega = 1.0
    # to evaluate eq_of_motion, the time parameter t is not explicitly needed
    # therefore we just set it to 0
    phi_dot, p_dot = eq_of_motion(0.0, [T, P], omega)
    # we calculate the magnitude of each phase space velocity
    # we use this a a value to colorcode the arrows in the folling plot
    M = np.sqrt(phi_dot**2 + p_dot**2)
```

1 Flow Field in Phase-Space

Explanation of quiver: quiver allows us to draw a vector field. The first two arguments (T and P in this case) specify the arrow position. The next two arguments give the arrow direction and length, where we have scaled each direction by its magnitude (given by M), to get unit vectors (resp. all vectors will have the same length). The fifth argument (here M) is used to color code each arrow individually, where the 'choice' of color is given by the cmap argument, specifying a *colormap*. The pivot argument tells the function to set the anchor point in the middle of the arrow. The other options handle the scaling of the arrows. Note that this is set up in a way, that the arrows will not be 1 unit long despite being unit vectors, because this would make the plot illegible.

2 Phase Space Trajectories

Call the function phase_space_trajectory for the following initial values (function parameter y_init): 1) [15°, 0.0] 2) [90°, 0.0] 3) [179°, 0.0] 4) [170°, -1.0]

You have to convert the angles from degrees to radians. This can be done via np.radians(<angle>). The value for the frequency ω was predefined in the variable omega which you are supposed to use. For the last example you should pass the extra argument has_initial_momentum=True as your last function parameter.

The plot command is called on the axis-object ax (defined before) via ax.plot(<arguments>). The first argument should be the angle φ , the second one the corresponding momentum p_{φ} . Immediately after this, you can pass a string to specify the color of your line: 'r' for red, 'g' for green, 'b' for blue, 'k' for black, etc.

If you want your lines thicker for better visibility, add lw=3.0 (or any desired floating point value) to you plot arguments.

In []: # call the function phase_space_trajectory here and plot your results
 # show the figure again
 fig

In []: